

1 LASER SHOCK PEENING TARGET

2

3 BACKGROUND OF THE INVENTION

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5 [0001] The present invention relates generally to manufacturing processes, and, more
6 specifically, to laser shock peening.

7 [0002] The strength of a metal workpiece may be improved by introducing compressive
8 residual stress in the external surface thereof. Shot peening is one conventional process to
9 introduce such residual compressive stress.

10 [0003] Another process uses the high energy of an industrial laser beam to burn an ablative
11 coating on the workpiece within a confinement layer such as water which causes an
12 instantaneous explosion, and the corresponding introduction of plastic deformation in the
13 workpiece surface for introducing the residual compressive stress. In such laser shock
14 peening (LSP) the laser operates in a pulse mode, with laser beam pulses being traversed
15 across the surface of the workpiece for introducing the residual stress therein.

16 [0004] The continuing development of the LSP process includes splitting the laser beam into
17 two opposite beams which strike opposite surfaces of the workpiece for particular advantage.
18 Since the main beam from the laser generator is split in two, its two components
19 simultaneously impact the opposite sides of the workpiece. However, the two split beams
20 require precise alignment with the workpiece to ensure that the simultaneous impact occurs at
21 oppositely aligned spots on the workpiece for increasing efficiency of operation.

22 [0005] One exemplary workpiece which may benefit from the use of the LSP process is the
23 airfoil commonly found in gas turbine engines in the compressor or turbine sections thereof.
24 A typical airfoil has a concave pressure side and an opposite convex suction side joined
25 together at chordally opposite leading and trailing edges, and extending in radial span from a
26 root to a tip. At the root is a platform which defines the inner flow boundary for the airfoil,
27 and an integral dovetail may extend below the platform for removably mounting the airfoil
28 blade into the corresponding slot of a supporting rotor.

29 [0006] Each engine includes many rows of such airfoils in the compressor and turbine

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1 sections thereof, and LSP is required for the full complement of airfoils in each row as
2 desired. Accordingly, the LSP process must be repeated to cover the substantial external
3 surface of each airfoil, and then repeated for the multiple airfoils for each rotor stage. The
4 corresponding manufacturing time accordingly increases the cost of the process.

5 [0007] The process necessarily begins with an alignment procedure to ensure that the two
6 opposite laser beams are aligned with the opposite sides at the same location of an individual
7 airfoil. The airfoil itself is suitably mounted in a fixture which is attached to the distal end of a
8 conventional, multiaxis computer numerically controlled (CNC) robot or manipulator. The
9 manipulator includes a computer controller which is suitably programmed in software for
10 controlling the desired movement of the workpiece airfoil relative to the stationary laser and
11 the beams emitted therefrom. In this way, the workpiece is precisely moved in
12 three-dimensional space for traversing the laser beams in a predetermined path over the
13 surface of the airfoil to effect complete laser shock peening thereof, which is simultaneous for
14 both sides of the airfoil.

15 [0008] Although the pressure and suction sides of the airfoil are curved in the typical
16 manner, the two sides generally face oppositely to each other which permits relatively quick
17 alignment of the two laser beams generally opposite with each other at about 180 degrees. A
18 conventional alignment procedure has been used for over a year in this country to prepare the
19 manipulator for the LSP processing of airfoil workpieces which have been sold and are found
20 in commercial use.

21 [0009] The alignment process includes a conventional alignment fixture in the form of a
22 rectangular beam having a transverse through hole in the distal end thereof. Two annular
23 cover plates are mounted in the common hole through opposite sides of the fixture, with each
24 plate including a center aperture transversely aligned with the opposite aperture. The two
25 plates have corresponding internal circular seats which adjoin each other along the
26 longitudinal center plane of the fixture, and support two target sheets trapped inside the
27 through hole.

28 [0010] The fixture may then be attached to the distal end of the manipulator which is
29 programmed to position the through hole and the aligned apertures thereat at the focal or
30 intersection point of the opposite laser beams. In this way, the laser beams may be directed

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1 through the corresponding opposite apertures in the alignment fixture to mark the target sheets
2 in the alignment procedure. The target sheets may be formed of a suitable material such as
3 photographic or burn paper, which will produce a visible mark when exposed to the laser
4 beam, typically produced by operating the high power LSP laser at a suitably low power
5 setting.

6 [0011] The corresponding burn marks on the target sheets may then be examined and
7 measured for any misalignment therebetween. The two laser beams should be aligned within
8 a few mils of each other, and any measured discrepancy thereof may be suitably adjusted by
9 adjusting the alignment of the laser beams using the conventional mirror adjustments found
10 therein.

11 [0012] The alignment procedure may be repeated one or more times as desired to confirm
12 the accuracy of alignment of the opposing laser beams relative to their intersection points on
13 the alignment fixture. The alignment fixture may then be simply removed and replaced by the
14 workpiece, such as an airfoil mounted to the manipulator on a suitable supporting fixture. The
15 manipulator is then suitably programmed to position the airfoil with its opposite sides facing
16 respective ones of the two laser beams so that the LSP process may be simultaneously effected
17 on opposite sides of the airfoil with accurate alignment of the two impact sites. The
18 manipulator then moves the mounted airfoil in three-dimensional space so that the two laser
19 beams may traverse the external surfaces of the airfoil for laser shock peening thereof.

20 [0013] As indicated above, an individual airfoil for a gas turbine engine has curved pressure
21 and suction sides which generally face oppositely to each other so that the oppositely aligned
22 laser beams may simultaneously impact the opposite sides of the airfoil at substantially the
23 same location in space. The airfoils typically twist from root to tip, yet the opposite external
24 surface thereof may still be suitably aligned with the two laser beams by rotating the airfoil
25 along its span axis to reposition the local sites of the airfoil between the opposite laser beams.

26 [0014] However, such twisting airfoils may be integrally formed with the supporting rotor in
27 a unitary or one-piece blisk assembly. In an exemplary compressor blisk, the full row of
28 airfoils extends radially outwardly from the supporting rotor with a relatively close spacing
29 around the circumference thereof, with the individual airfoils nesting between the next
30 adjacent airfoils. The adjacent airfoils in a blisk therefore prevent the use of laser beams

1 aligned oppositely about 180 degrees apart due to the blocking effect thereof.

2 [0015] Accordingly, the LSP process requires that the two laser beams be realigned at an
3 included angle substantially less than 180 degrees, and even down to a small acute included
4 angle as low as about 20 degrees. In this way, the two laser beams may be directed to the
5 opposite sides of an individual airfoil in a compressor blisk to avoid the obstruction of the next
6 adjacent airfoils in the blisk.

7 [0016] In this configuration of the oblique laser beams, the initial alignment thereof becomes
8 more complex. Since the conventional alignment fixture in the form of a rectangular beam
9 has a small but substantial thickness, and the target apertures in the distal end thereof extend
10 transversely through the fixture, the fixture itself introduces self-obstruction with the oblique
11 laser beams particularly at small or acute included angles therebetween.

12 [0017] In order to effectively use the conventional alignment fixture with the oblique laser
13 beams, one of the two cover plates is removed for removing the self-blocking effect thereof,
14 and the target sheets are simply taped into the exposed through hole against the remaining
15 cover plate. The so-modified alignment fixture is then conventionally used in the alignment
16 procedure, with the oblique laser beams having elliptical projections on the target sheets due
17 to the relative inclination therewith.

18 [0018] The elliptical laser beam projections increase the difficulty of aligning the opposite
19 beams, and the alignment process requires iteration by replacing the marked target sheets with
20 clean sheets again taped into the fixture hole. However, taping and untaping of the target
21 sheets lacks accuracy or repeatability of location and further complicates the alignment
22 procedure.

23 [0019] The alignment procedure for the oblique laser beams can therefore require up to
24 about a half a day which is a substantial expenditure of time, which is typically repeated each
25 and every day of the laser shock peening process for ensuring accuracy thereof. The
26 alignment procedure therefore increases the overall time for laser shock peening the multitude
27 of workpieces, and correspondingly increases the cost of manufacture.

28 [0020] Accordingly, it is desired to provide an improved laser shock peening target for
29 reducing time of alignment of oblique laser beams.

1 BRIEF DESCRIPTION OF THE INVENTION

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3 [0021] A laser target includes a shank having a first wedge converging from a step to a distal
4 end of the wedge. A complementary second wedge is mounted on the step and converges
5 with the first wedge. The two wedges have respective target apertures aligned with each other
6 transversely therethrough.

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8 BRIEF DESCRIPTION OF THE DRAWINGS

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10 [0022] The invention, in accordance with preferred and exemplary embodiments, together
11 with further objects and advantages thereof, is more particularly described in the following
12 detailed description taken in conjunction with the accompanying drawings in which:

13 [0023] Figure 1 is a schematic view of a computer numerically controlled manipulator
14 configured for positioning an exemplary workpiece blisk between oblique laser beams for
15 conducting laser shock peening thereof.

16 [0024] Figure 2 is a schematic view, like Figure 1, of the manipulator and laser during
17 alignment of the two laser beams using an improved laser target mounted to the manipulator.

18 [0025] Figure 3 is a isometric view of the laser target illustrated in Figure 2 in accordance
19 with an exemplary embodiment.

20 [0026] Figure 4 is an exploded view of the distal end of the target shown in Figure 3
21 illustrating assembly thereof.

22 [0027] Figure 5 is a partly sectional schematic view of the alignment configuration of Figure
23 2 in more detail.

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25 DETAILED DESCRIPTION OF THE INVENTION

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27 [0028] Illustrated schematically in Figure 1 is a conventional multiaxis, computer
28 numerically controlled (CNC) robot or manipulator 10 having a supporting bracket 12 at a
29 distal end thereof on which may be suitably mounted a workpiece 14 in the exemplary form of
30 a gas turbine engine compressor blisk having two integral rows of individual airfoils 16 in a

1 unitary assembly. The manipulator may have any conventional form such as the Motoman
2 UP165 Robot commercially available from the Yaskawa Company of West Carrollton, Ohio.
3 The manipulator includes an arm articulated for movement along six axes of rotation so that
4 the distal end bracket 12 may be located in three-dimensional space along the typical three
5 axes of translation and three axes of rotation for positioning the workpiece 14 as desired
6 within the range of the manipulator.

7 [0029] The manipulator includes a computer controller 18 (CNC) which can be
8 conventionally programmed with suitable software for controlling the movement of the
9 robotic arm, and in particular the workpiece mounted at the end thereof. In this way, the
10 workpiece may be precisely located and orientated in three-dimensional space as desired for
11 undergoing laser shock peening (LSP).

12 [0030] More specifically, cooperating with the manipulator in a combined apparatus is a
13 high power industrial laser 20 and cooperating optical elements or optics 22 disposed in
14 optical alignment therewith. The laser system including the laser 20 and optics 22 may have
15 any conventional configuration and typically includes a conventional YAG laser having
16 sufficient power for effecting laser shock peening. And, the optical elements include
17 adjustable mirrors having micrometer mounting gimbals which permit precise optical
18 alignment of the laser beam 24 emitted from the laser during operation.

19 [0031] For the LSP process, the optical elements of the laser system illustrated in Figure 1
20 include a suitable beam splitter and mirrors for splitting the initially produced laser beam into
21 two laser beam components which are suitably directed at an individual airfoil 16 of the
22 workpiece 14.

23 [0032] As indicated above, each airfoil 16 illustrated in Figure 1 has a generally concave
24 pressure side and an opposite generally convex suction side extending between chordally
25 opposite leading and trailing edges and extending from a radially inner root to a radially outer
26 tip. Each airfoil is integrally formed with the supporting rotor in a one-piece unitary blisk
27 configuration. In this way, a full row of airfoils extends integrally outwardly from the
28 perimeter of the rotor, and the exemplary blisk illustrated in Figure 1 includes two integral
29 stages of airfoils therein.

30 [0033] Each of the airfoils includes twist or stagger from root to tip, and the airfoils are

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1 spaced closely together and nested around the circumferential of the blisk. Accordingly, each
2 airfoil is hidden in part between the next adjacent airfoils on opposite circumferential sides
3 thereof, and will block line-of-sight of laser beams directed at the surfaces of the airfoil at
4 about 180 degrees apart.

5 [0034] Accordingly, the optics of the laser system illustrated in Figure 1 are configured for
6 directing the two split laser beams 24 obliquely with each other at an included angle A
7 therebetween which is less than 180 degrees, and may be down to a small acute angle of about
8 20 degrees, for example. In this way, the two laser beams may be directed to the opposite
9 surfaces of an individual airfoil without obstruction from the next adjacent airfoils in the blisk.
10 The laser shock peening process may then be effected by guiding the two laser beams within
11 the available space on the opposite sides of an individual airfoil, and avoid the obstruction or
12 shadowing by the next adjacent airfoils either in the same row or from the next row of the
13 exemplary two-row blisk configuration.

14 [0035] As indicated above, the oblique laser beams 24 require precise alignment with each
15 other to ensure that they simultaneously impact the opposite sides of the airfoil workpiece
16 with suitably precise alignment, and with minimal lateral offset therebetween. Accordingly,
17 Figure 2 illustrates a laser target 26 suitably mounted to the distal end bracket of the
18 manipulator 10, instead of the workpiece, for use in the initial alignment with the laser system.

19 [0036] The laser target 26 is illustrated in more detail in isolation in Figure 3 and may be
20 formed of any suitable material such as metal. The target includes a straight rectangular shank
21 28 having an integral or unitary first ramp or wedge 30 supporting thereto a complementary
22 second ramp or wedge 32. The first wedge is integral with the distal end of the shank 28 and
23 converges from a recess or step 34 in the shank to the distal end of the first wedge itself.

24 [0037] The second wedge 32 is a discrete component suitably fixedly mounted on the step
25 34 and converges with the first wedge 30 to the corresponding distal ends thereof. The
26 opposite proximal end of the shank 28 is fixedly joined to a base plate 36 which is suitably
27 configured for mounting the target to the bracket on the distal end of the manipulator
28 illustrated in Figures 1 and 2. In this way, the shank 28 extends perpendicularly outwardly
29 from the base plate 36 to position the two wedges 30,32 in the three-dimensional space
30 illustrated in Figure 2 for aligning the two split laser beams 24.

1 [0038] More specifically, Figure 4 illustrates additional details of the distal end of the target
2 illustrated in Figure 3. The first and second wedges 30,32 have respective target holes or
3 apertures 38 aligned with each other transversely or laterally therethrough. The target
4 apertures are also preferably mounted in the middle of the width of the two wedges as close as
5 practical to the distal ends thereof.

6 [0039] The two wedges 30,32 are preferably mirror images of each other, and further
7 include respective inboard flat seats 40 adjoining each other for supporting one or more target
8 sheets 42 between the target apertures 38. The two wedges 30,32 are collectively arranged in
9 a triangle terminating in an apex at the distal ends of the two wedges. The wedge triangle
10 illustrated in Figure 3 is preferably symmetrical and defines an isosceles triangle having an
11 acute included angle B of about 25 degrees for example.

12 [0040] The two wedges 30,32 also include respective external flat faces 44 in which the
13 target apertures 38 are mounted flush. In this way, the target apertures are mounted in the
14 smooth external faces 44 of the two wedges, with the wedges having the small included angle
15 B therebetween for presenting the apertures to the two laser beams illustrated in Figure 2 with
16 minimal obstruction by the target components immediately surrounding the target apertures.

17 [0041] As illustrated in Figure 2, the apex end of the target may be positioned by the
18 manipulator to face the two laser beams 24. The longitudinal axis of the target 26 is
19 preferably aligned in the plane of the two laser beams 24 so that the two laser beams 24 are
20 incident with the respective target apertures 38.

21 [0042] In the preferred embodiment illustrated in Figures 3 and 4, the target apertures 38 are
22 oval, with corresponding major axes being normal or perpendicular with the shank step 34.
23 The exemplary oval configuration illustrated in Figure 4 includes straight sides extending
24 along the longitudinal axis of the shank terminating in semi-circular ends which define a
25 generally race-track configuration.

26 [0043] Since the target apertures 38 extend transversely through the corresponding wedges
27 30,32, they correspondingly decrease in thickness or depth between the shank step 34 and the
28 common apex of the wedges. In this way, the target apertures 38 are thinner near the distal
29 end of the wedges which is closest to the incident laser beams, and thicker at the base ends of
30 the wedges where they join at the step 34.

1 [0044] As shown in Figure 4, each of the two seats 40 includes a respective recess 46
2 aligned with each other around the respective target apertures 38 to define a pocket for
3 receiving the target sheet 42. The two recesses 46 preferably have equal depths C for aligning
4 the mating plane of two target sheets 42 with the mating plane of the corresponding seats 40
5 of the two wedges 30,32. This is best illustrated in Figure 5 wherein the two seats 40 adjoin
6 each other along the longitudinal centerline plane of the shank and wedges. This positions the
7 two sheets identically below the respective target apertures 38 on opposite sides of the target.

8 [0045] As illustrated in Figures 3-5, the second wedge 32 is removably joined to the first
9 wedge 30 by one or more threaded bolts 48, such as the pair illustrated. The bolts extend
10 through holes in the second wedge 32 and engage threaded apertures in the first wedge 30 for
11 clamping together the two wedges, and clamping therebetween the two target sheets 42. The
12 two bolts 48 are preferably located between the target apertures 38 and the shank 28 to prevent
13 their obstruction of the incident laser beams. The heads of the bolts may be mounted
14 substantially flush in the second wedge if desired.

15 [0046] The target sheets 42 illustrated in Figure 5 may have any conventional composition
16 such as photographic paper. The combined thickness of the two sheets 42 is preferably larger
17 than the combined depth of the recesses 46 so that clamping of the second wedge to the first
18 wedge correspondingly compresses and clamps the two sheets tightly therebetween and inside
19 the corresponding recesses 46. The recesses 46 illustrated in Figure 4 have a suitable
20 configuration for surrounding the respective target apertures 38, and the target sheets 42 are
21 suitably configured for being trapped within the corresponding recesses. In this way, the two
22 target sheets are accurately clamped between the two wedges with identical orientation on
23 opposite sides of the target for receiving the corresponding incident laser beams 24.

24 [0047] As shown in Figure 4 each of the wedge faces 44 preferably includes a respective
25 crosshair or crossmark 50 around the target apertures 38 for use in centering the laser beam
26 therein during the alignment process. The visual crosshairs permit the operator to quickly
27 align the two laser beams with a rough accuracy. The crosshairs also permit later adjustment
28 of the laser beam alignment for reducing or minimizing any offset between the opposite
29 beams.

30 [0048] More specifically, the improved target illustrated in Figures 3-5 may be used with the

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1 manipulator 10 and laser system illustrated in Figure 2 for quickly aligning the two laser
2 beams 24 for accurate laser shock peening of the exemplary blisk workpiece 14 illustrated in
3 Figure 1 with the oblique laser beams. As initially illustrated in Figure 4, the second wedge
4 32 is initially assembled to the first wedge 30 with preferably a pair of the target sheets 42
5 clamped therebetween as illustrated in Figure 5. The so assembled target is then suitably
6 mounted to the manipulator 10 in Figure 2 by joining the target base plate to the bracket at the
7 distal end of the manipulator arm.

8 [0049] The manipulator is programmed with suitable software for carrying or moving the
9 target on the distal end of the arm to position the opposite target apertures 38 in rough
10 alignment with the two laser beams 24. For example, conventional, low power pointing laser
11 beams may be used initially for the rough alignment of the target apertures with the
12 corresponding paths for the main laser beams in a conventional manner.

13 [0050] The high power laser 20 itself may then be operated in a relatively low power mode
14 to emit the split laser beams 24 to mark or burn the target sheets 42 exposed within the two
15 target apertures. Figure 5 illustrates schematically two burn marks thusly created in the two
16 target sheets 42 exposed within the two target apertures 38. Any lateral offset D between the
17 two burn marks may then be suitably measured, either roughly by eye or more accurately
18 using a scale.

19 [0051] The offset of the two laser beams within the two target apertures 38 may be reduced
20 or minimized by correspondingly adjusting alignment of the laser beams. This adjustment is
21 effected in a conventional manner by adjusting, for example, the micrometer gimbals
22 supporting the directional mirrors in the laser optics. For example, if one burn mark is slightly
23 higher than the opposite burn mark, its optical alignment may be lowered relative thereto.

24 [0052] The second wedge 32 may then be disassembled from the first wedge for removing
25 and replacing the two target sheets, and reassembling the wedges. The laser may then be
26 operated again to mark the replacement target sheets to confirm the alignment of the two
27 beams. If further adjustment is required, the process is repeated. Nevertheless, the use of the
28 wedge target greatly simplifies the alignment procedure and substantially reduces the time
29 required therefor to merely minutes instead of a half a day for the obliquely aligned laser
30 beams.

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1 [0053] As illustrated in Figure 5, the wedge-shaped target 26 is preferably aligned with the
2 two laser beams 24 generally symmetrically therewith so that each laser beam 24 is incident to
3 each target aperture 38 at substantially equal incidence angles. In other words, the included
4 angle A between the two laser beams 24 is split equally by the mating plane of the two wedges
5 on opposite sides of which the two target sheets 42 are disposed.

6 [0054] In this way, the initially round laser beams 24 effect elliptical projections thereof
7 inside the respective target apertures 38. The target apertures 38 are preferably oval as
8 described above for surrounding the respective elliptical projections. And, the major axes of
9 the elliptical beam projection and target apertures are preferably coextensive.

10 [0055] Due to the wedge configuration of the target, the target apertures vary in thickness
11 being thinnest at the common apex of the wedges which first faces the incident laser beams
12 and increases in thickness away therefrom. The converging wedges and the relatively sharp
13 common apex thereof provides an enhanced target within the apertures, with the surrounding
14 material of the apertures providing minimal obstruction, if any, to the incident laser beams.

15 [0056] Accordingly, the otherwise conventional CNC manipulator 10 and laser system
16 illustrated in Figure 2 may be quickly and easily aligned using the improved wedge-shaped
17 target 26. The target apertures 38 have a precise and predetermined location relative to the
18 base plate, and therefore relative to the bracket at the distal end of the manipulator arm.

19 [0057] Accordingly, upon alignment of the laser optics, the target 26 itself may be simply
20 removed from the manipulator arm and substituted or replaced with the intended workpiece
21 14, such as the exemplary workpiece blisk. The computer controller 18 of the manipulator
22 may then be loaded with the corresponding software for controlling the desired path of the
23 workpiece relative to the so-aligned laser beams 24 for effecting laser shock peening of the
24 external surface of the workpiece where desired. The laser 20 may then be operated in its high
25 power, LSP mode of operation for accurately laser shock peening the opposite sides of each
26 airfoil 16 of the exemplary workpiece blisk.

27 [0058] While there have been described herein what are considered to be preferred and
28 exemplary embodiments of the present invention, other modifications of the invention shall be
29 apparent to those skilled in the art from the teachings herein, and it is, therefore, desired to be
30 secured in the appended claims all such modifications as fall within the true spirit and scope of

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1 the invention.

2 [0059] Accordingly, what is desired to be secured by Letters Patent of the United States is

3 the invention as defined and differentiated in the following claims in which we claim: